## SHORT COMMUNICATIONS

Contributions intended for publication under this heading should be expressly so marked; they should not exceed about 1000 words; they should be forwarded in the usual way to the appropriate Co-editor; they will be published as speedily as possible.

Acta Cryst. (1990). A46, 423
Chirality in rotational superposition. By R. DiAmond, Medical Research Council Laboratory of Molecular Biology, Hills Road, Cambridge, CB2 2QH, England.
(Received 23 November 1989; accepted 8 February 1990)


#### Abstract

It is shown that in the rotational superposition method proposed by Diamond (1988), which always produces orthogonal transformations with positive determinants, a simple test exists for the existence of an enantiomorphic relationship between the vector sets, and, if required, an enantiomorphous orthogonal superposition may be provided at no extra cost.


In a recently published paper [(Diamond, 1988), here referred to as (I)] an analysis of the rotational superposition problem was presented using the quaternion variables, in terms of which the quadratic residual after rotational fitting was shown to be a quadratic form of order four. It was also shown that the orthogonal transformations so generated necessarily have positive determinants even if the vector sets to be superposed have opposite chirality: a situation which may be troublesome to other methods.

In the notation of that paper it was shown that if a vector set $\mathbf{x}$ is to be superimposed on $\mathbf{X}$ using an orthogonal transformation, $\mathbf{R}$, with positive determinant, so as best to satisfy

$$
\begin{equation*}
\mathbf{X}=\mathbf{R} \mathbf{x} \tag{1}
\end{equation*}
$$

then $\mathbf{R}$ may be constructed from a four-dimensional vector, $\boldsymbol{\rho}$ (a unit quaternion), which is the eigenvector of largest eigenvalue of a matrix $\mathbf{P}$ which, in turn, is constructed from the three-row rectangular matrices $\mathbf{X}$ and $\mathbf{x}$.

If the eigenvalues of $\mathbf{P}$ are $p_{1}$ through $p_{4}$, arranged in descending order, with associated eigenvectors $\boldsymbol{\rho}_{1}$ through $\boldsymbol{\rho}_{4}$, then, from equation (23) of (I),

$$
\begin{equation*}
E_{\min }=E_{0}-2 p_{i} \tag{2}
\end{equation*}
$$

where

$$
\begin{align*}
E & =\sum W(\mathbf{X}-\mathbf{R x}) \cdot(\mathbf{X}-\mathbf{R x})  \tag{3}\\
E_{0} & =\sum W(\mathbf{X}-\mathbf{x}) \cdot(\mathbf{X}-\mathbf{x})
\end{align*}
$$

with weights $W$, in which $\mathbf{x}$ and $\mathbf{X}$ are, for the moment, treated as individual corresponding column vectors.

If we use a prime to denote the fitting, by proper rotation, of $\mathbf{R}^{\prime} \mathbf{x}$ onto - $\mathbf{X}$, the enantiomer of $\mathbf{X}$, then likewise

$$
\begin{align*}
& E^{\prime}=\sum W\left(\mathbf{X}+\mathbf{R}^{\prime} \mathbf{x}\right) \cdot\left(\mathbf{X}+\mathbf{R}^{\prime} \mathbf{x}\right)  \tag{4}\\
& E_{0}^{\prime}=\sum W(\mathbf{X}+\mathbf{x}) \cdot(\mathbf{X}+\mathbf{x})
\end{align*}
$$

$$
\begin{equation*}
E_{\text {min }}^{\prime}=E_{0}^{\prime}-2 p_{1}^{\prime} \tag{5}
\end{equation*}
$$

However, negating $\mathbf{X}$ or $\mathbf{x}$, but not both, negates $\mathbf{P}$ and therefore all of its eigenvalues, so that

$$
\begin{equation*}
p_{1}^{\prime}=-p_{4} . \tag{6}
\end{equation*}
$$

Equations (3) and (4) give

$$
\begin{align*}
E_{0} & =\operatorname{tr}\left[(\mathbf{X}-\mathbf{x}) \mathbf{W}\left(\mathbf{X}^{T}-\mathbf{x}^{T}\right)\right] \\
& =\operatorname{tr}\left(\mathbf{X W} \mathbf{X}^{T}\right)-2 \operatorname{tr}\left(\mathbf{x} \mathbf{W} \mathbf{X}^{T}\right)+\operatorname{tr}\left(\mathbf{x} \mathbf{W} \mathbf{x}^{T}\right) \\
E_{0}^{\prime} & =\operatorname{tr}\left[(\mathbf{X}+\mathbf{x}) \mathbf{W}\left(\mathbf{X}^{T}+\mathbf{x}^{T}\right)\right]  \tag{7}\\
& =\operatorname{tr}\left(\mathbf{X} \mathbf{W} \mathbf{X}^{T}\right)+2 \operatorname{tr}\left(\mathbf{x} \mathbf{W} \mathbf{X}^{T}\right)+\operatorname{tr}\left(\mathbf{x} \mathbf{W} \mathbf{x}^{T}\right)
\end{align*}
$$

in which $\mathbf{x}$ and $\mathbf{X}$ are again rectangular and $\mathbf{W}$ is diagonal. Therefore

$$
\begin{equation*}
E_{\min }^{\prime}-E_{\min }=4 \operatorname{tr}\left(\mathbf{x} \mathbf{W} \mathbf{X}^{T}\right)+2 p_{1}+2 p_{4} \tag{8}
\end{equation*}
$$

But

$$
\begin{align*}
p_{1}+p_{2}+p_{3}+p_{4} & =\operatorname{tr} \mathbf{P}=\operatorname{tr} \mathbf{Q} \\
& =\operatorname{tr} \mathbf{M}+\operatorname{tr} \mathbf{M}^{T}-2 \operatorname{trI} \cdot \operatorname{tr} \mathbf{M}  \tag{9}\\
& =-4 \operatorname{tr}\left(\mathbf{x} \mathbf{W} \mathbf{X}^{T}\right)
\end{align*}
$$

from equations (17) and (22) of (I). Therefore

$$
\begin{equation*}
E_{\min }^{\prime}-E_{\min }=p_{1}-p_{2}-p_{3}+p_{4} \tag{10}
\end{equation*}
$$

Thus, if the right-hand side of (10) is negative it is certain that $\mathbf{x}$ can be superimposed on - $\mathbf{X}$ more closely than on $\mathbf{X}$, which fact may thus be established before transforming any coordinates. Furthermore, the associated rotation matrix, $\mathbf{R}^{\prime}$, may be constructed from $\rho_{4}$ in the same way that $\mathbf{R}$ is constructed from $\rho_{1}$ using equation (7) of (I). Routines used to find $p_{1}$ normally provide all eigenvalues anyway.

## Reference

Diamond, R. (1988). Acta Cryst. A44, 211-216.

